

IN THE SPECIFICATION:

Amend paragraph 0062 (referring to the U.S. published application) as follows:

[0062] As shown in FIG. 1, the humanoid robot 1 has sensors 11a, 11b, and ~~11c~~ 11c each of which is one aspect of a detecting device, a communication unit 12, a relative position posture calculating unit 13 that is one aspect of an image generating device, a joint actuator 14, an image generating device, an image processing unit 15 that is one aspect of a nimbus generating device and a combined image generating device, a storage unit 16, and a communication unit 17 that is one aspect of a communication device. Further, the HMD 2 has sensors 21a and 21b each of which is one aspect of the detecting device, communication units 22 and 23, a three-dimensional image displaying unit 24 that is one aspect of an image display processing device, and a control unit 25.

Amend paragraph 0068 (referring to the U.S. published application) as follows:

[0068] The HMD 2 is, as shown in FIG. 3, a goggle-type display which is worn on the head portion of an observer. The HMD 2 is a transmissive-type head mount display which transmits a light via a part of an image projecting unit in front of the eyes of the observer where an image is not projected. Therefore, the observer can see an actual object (which is an object that actually exists, having an opposite meaning to the three-dimensional image of computer graphics), one example of which is the humanoid robot 1, through the part of the image projecting unit of the HMD 2 where an image is not projected.